

How to inject PSI5 Sensor Data via CAN -Seskion GmbH-

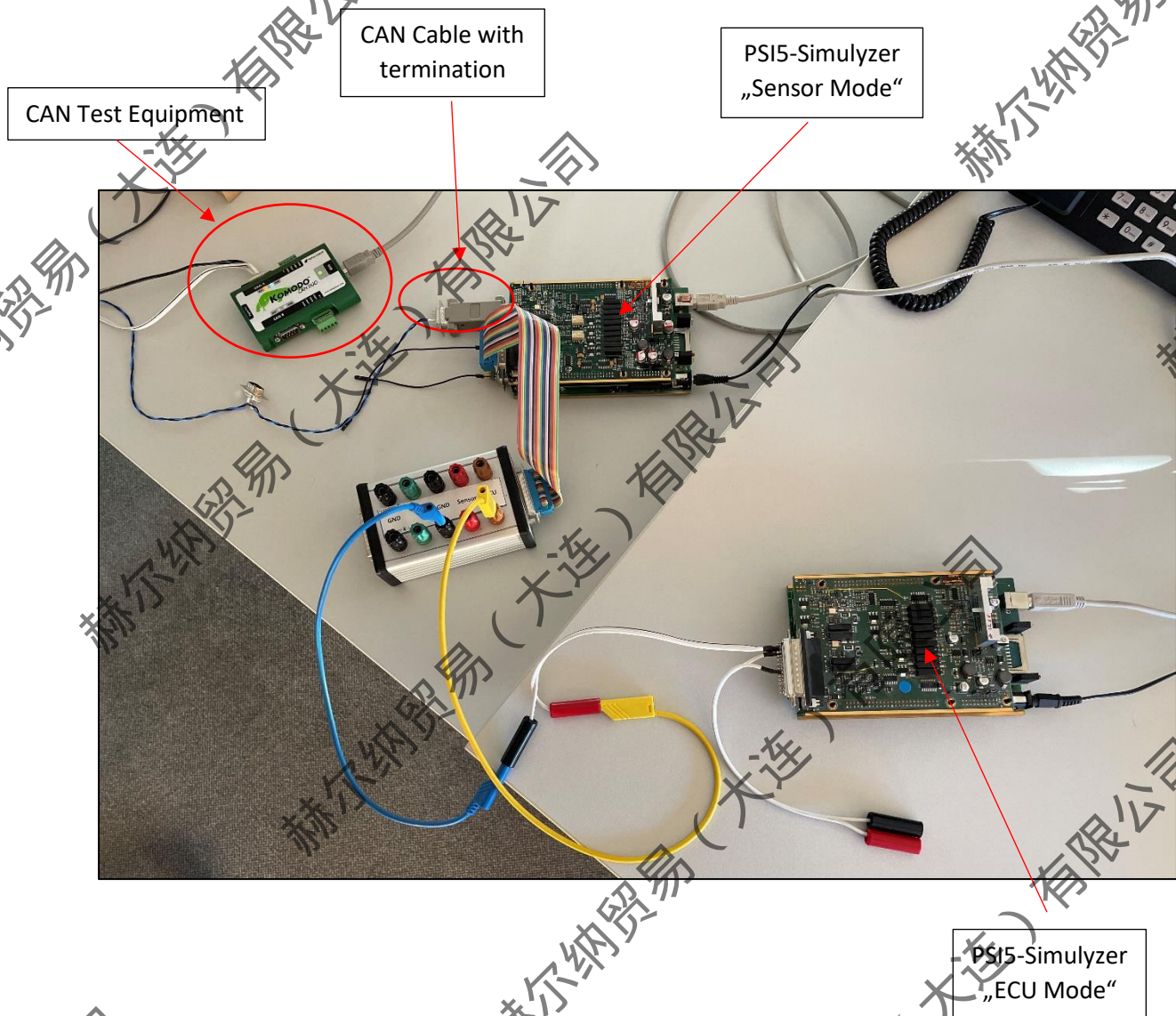
Content:

- Test setup: CAN – Simulyzer Sensor-Mode – Simulyzer ECU-Mode
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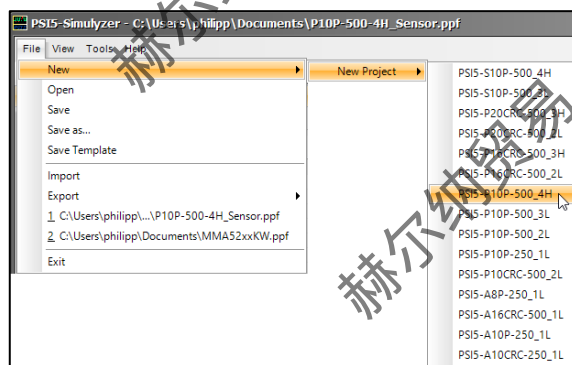
Test setup: CAN – Simulyzer Sensor-Mode – Simulyzer ECU-Mode



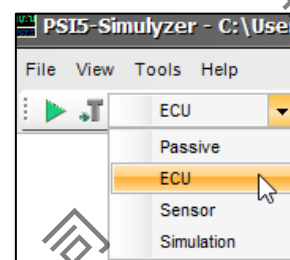
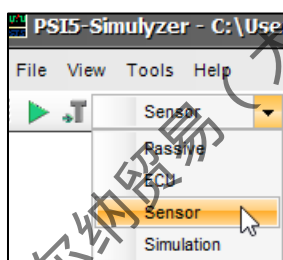
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CAN – Simulyzer Sensor-Mode – Simulyzer ECU-Mode

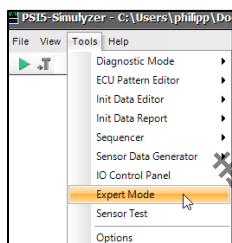
First of all you have to connect the two simulyzers and start the GUI software twice. With both windows open, you must click on the menu group **File** and select the sub-items **New** and **New Project**. Here you can set the compatibility. In our example we have created this with the PSI5-P10P-500_4H compatibility.



When you have opened the new projects in both open software applications, you have to set the connected Sensor simulyzer as **Sensor** and the other simulyzer as **ECU**.

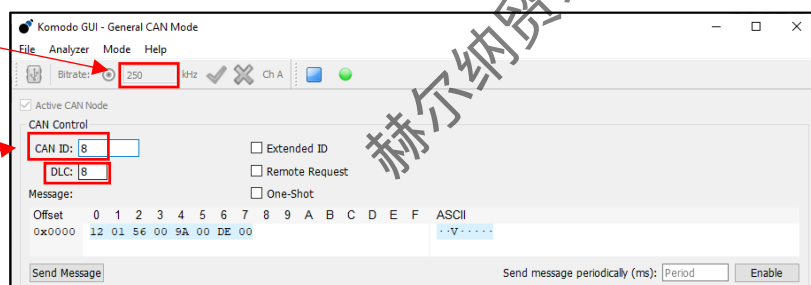
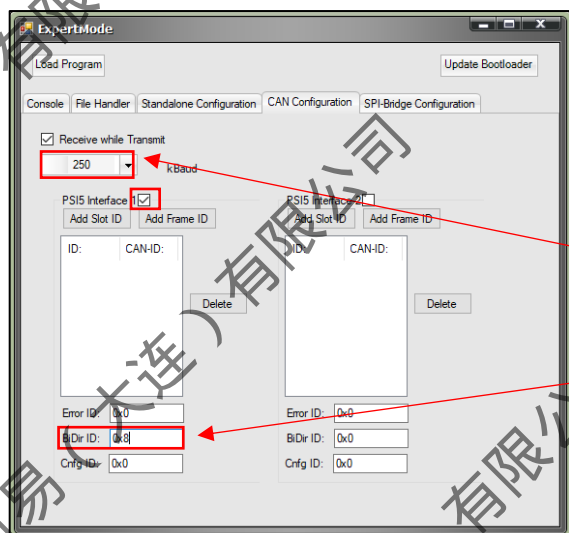


Next you have to select **Tools** in the sensor software and go to **Expert Mode** and then to **CAN Configuration**.



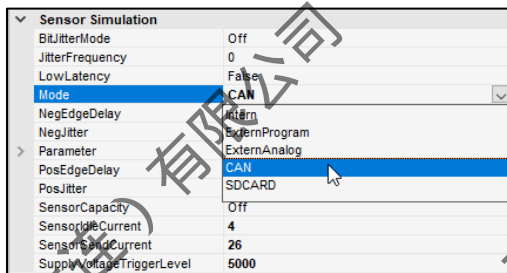
Now you have to transfer the values in your CAN Test-Software GUI into the CAN Configuration so that they match. The **kBaud/kHz** and the **CAN ID/BitDir ID** must be the same in both configurations. In Expert mode you have to check the **PSI5-Interface 1** checkbox and enter "8" in the DLC field of the CAN Test-Software GUI. We support only 4 slots with a maximum bit length of 16 bit, coded in Little Endian. The slots are 16 bit aligned.

Offset	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0x0000	12	01	56	00	9A	00	DE	00								
	1	2	3	4												



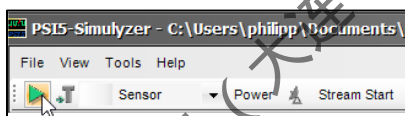
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For the CAN communication to work, the mode must be changed from Internal to **CAN** in the left settings under Sensor Simulation.

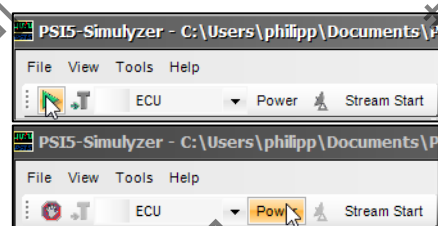


Now you can click on the **green arrow** in the sensor software and in the ECU software also on the **green arrow** and additionally on **Power**.

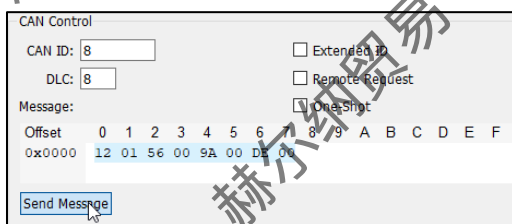
Sensor-Mode Software:



ECU-Mode Software



Now when you click on **Send Message** in CANTest-Software GUI, you will see this message in both software windows.



Sensor-Software Data:

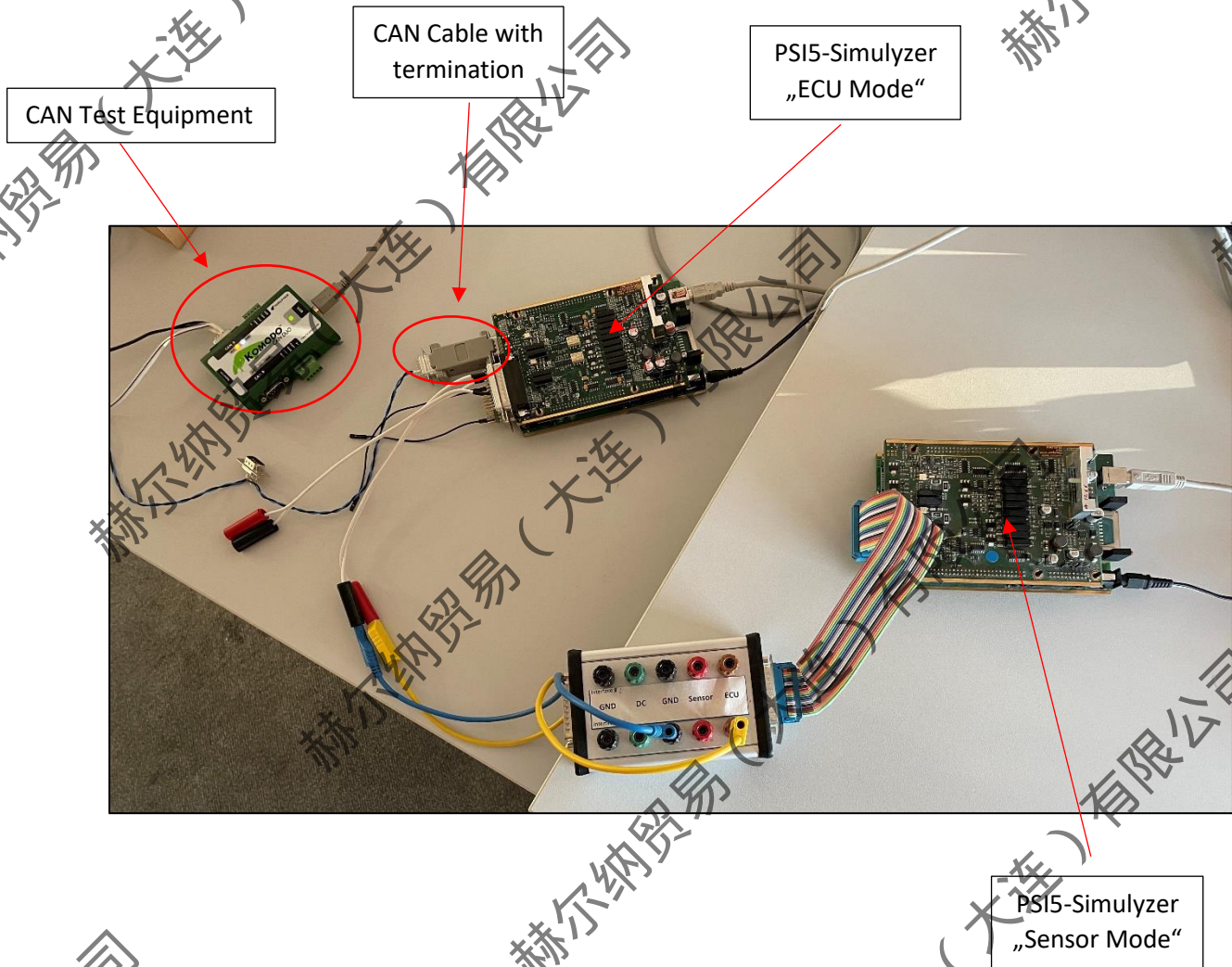
Time [µsec]	Ch	Data	Slot	Error	Parity/C...	dataRegA
162703515	0	Sync				
162703453	0	0x0de	0x3	0x0	0	0x0de
162703453	0		Sig4		0x0de	
162703336	0	0x9a	0x2	0x0	0	0x9a
162703336	0		Sig3		0x9a	
162703229	0	0x56	0x1	0x0	0	0x56
162703229	0		Sig2		0x56	
162703138	0	0x112	0x0	0x0	1	0x112
162703138	0		Sig1		0x112	

ECU-Software Data:

Time [µsec]	Ch	Data	Slot	Error	Parity/C...	dataRegA
8155637	1	Sync				
8155635	0	Sync				
8155574	0	0x0de	0x3	0x0	0	0x0de
8155574	0		Sig4		0x0de	
8155457	0	0x9a	0x2	0x0	0	0x9a
8155457	0		Sig3		0x9a	
8155380	0	0x56	0x1	0x0	0	0x56
8155350	0		Sig2		0x56	
8155259	0	0x112	0x0	0x0	1	0x112
8155259	0		Sig1		0x112	

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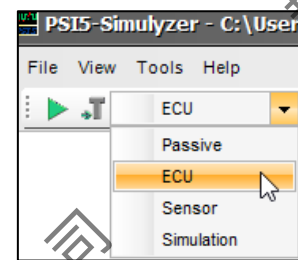
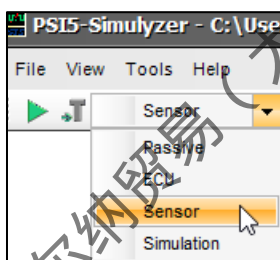
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CAN – Simulyzer ECU-Mode – Simulyzer Sensor-Mode

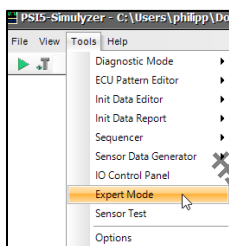
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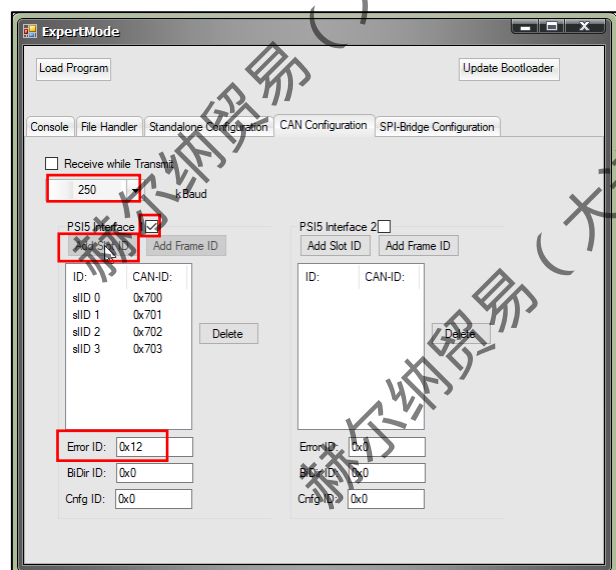
When you have opened the new projects in both open software applications, you have to set the connected Sensor simulyzer as **Sensor** and the other simulyzer as **ECU**.



Next you have to select **Tools** in the sensor software and go to **Expert Mode** and then to **CAN Configuration**.



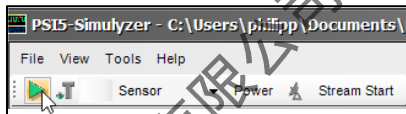
Here you can assign up to four Slot IDs by clicking on **Add Slot ID**. The kBaud number must also match the kHz number in the CAN Test-Software GUI and the check mark for **PSI Interface 1** must also be set. As **Error ID** you can enter a desired number.



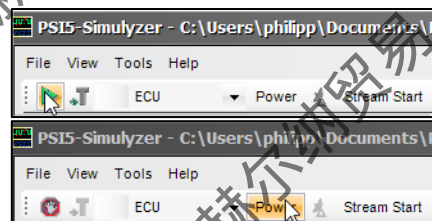
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Now you can click on the **green arrow** in the sensor software and in the ECU software also on the **green arrow** and additionally on **Power**.

Sensor-Mode Software:



ECU-Mode Software:



In the CAN Test-Software GUI you will now see the following responses:

ms.ms.us	ID	RTR	DLC	Data
137.46.058.650	0x702	0	4	46 04 00 00
137.46.058.994	0x703	0	4	47 00 00 00
137.46.059.330	0x700	0	4	48 00 00 00
137.46.059.674	0x701	0	4	49 00 00 00
137.46.060.010	0x702	0	4	4A 04 00 00
137.46.060.350	0x703	0	4	4B 00 00 00
137.46.060.694	0x700	0	4	4C 04 00 00
137.46.061.038	0x701	0	4	4D 00 00 00
137.46.061.378	0x702	0	4	4E 00 00 00
137.46.061.726	0x703	0	4	4F 04 00 00
137.46.062.066	0x700	0	4	50 00 00 00
137.46.062.410	0x701	0	4	51 04 00 00
137.46.062.746	0x702	0	4	52 04 00 00
137.46.063.090	0x703	0	4	53 00 00 00
137.46.063.426	0x700	0	4	54 04 00 00
137.46.063.770	0x701	0	4	55 00 00 00
137.46.064.109	0x702	0	4	56 00 00 00
137.46.064.453	0x703	0	4	57 04 00 00
137.46.064.789	0x700	0	4	58 04 00 00
137.46.065.137	0x701	0	4	59 00 00 00